

ESCAPING THE VERIFIER: LEARNING TO REASON VIA DEMONSTRATIONS

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ABSTRACT

Training Large Language Models (LLMs) to reason often relies on Reinforcement Learning (RL) with task-specific verifiers. However, many real-world reasoning-intensive tasks lack verifiers, despite offering abundant expert demonstrations that remain under-utilized for reasoning-focused training. We introduce **RARO** (Relativistic Adversarial Reasoning Optimization) that learns strong reasoning capabilities from only expert demonstrations via **Inverse Reinforcement Learning**. Our method sets up an adversarial game between a **policy** and a **relativistic critic**: the policy learns to mimic expert answers, while the critic aims to identify the experts among (expert, policy) answer pairs. Both the policy and the critic are trained jointly and continuously via RL, and we identify the key stabilization techniques required for robust learning. Empirically, RARO significantly outperforms strong verifier-free baselines on all of our evaluation tasks — Countdown, DeepMath, and Poetry Writing — and enjoys the same robust scaling trends as RL with verifiers. These results demonstrate that our method effectively elicits strong reasoning performance from expert demonstrations alone, enabling robust reasoning learning even when task-specific verifiers are unavailable.

1 INTRODUCTION

Recent advances in Large Language Models (LLMs) have been driven substantially by improvements in their *reasoning* abilities. Reasoning enables LLMs to perform deliberate intermediate computations before producing answers to the user queries, proposing candidate solutions and self-corrections. Much of this progress has been enabled via Reinforcement Learning (RL) on *verifiable* tasks such as mathematics and competitive programming (DeepSeek-AI et al., 2025; Yang et al., 2025a; Shao et al., 2024; Luo et al., 2025). Notably, recent work has demonstrated that RL with Verifiable Rewards (RLVR) can enable LLMs to develop robust reasoning capabilities without any additional supervision (DeepSeek-AI et al., 2025). A growing body of work further improves the efficiency and stability of such RL algorithms on verifiable tasks, such as DAPO (Yu et al., 2025) and GSPO (Zheng et al., 2025). However, comparatively little attention has been paid to developing reasoning abilities on *non-verifiable* tasks, where task-specific verifiers are unavailable.

Yet, in many impactful and challenging tasks — such as analytical writing, open-ended research, or financial analysis — LLM outputs are not directly verifiable due to hard-to-specify criteria, wide variation among acceptable answers, and other practical constraints. A popular approach in these settings is Reinforcement Learning from Human Feedback (RLHF) (Ouyang et al., 2022; Rafailov et al., 2023), but they require collecting human preferences beyond demonstration data, which is often a time-consuming and expensive process.

Without preference data, the typical approach to improving LLM performance in these domains is to conduct Supervised Fine-Tuning (SFT) on expert demonstration data via the next-token prediction objective. However, such methods, even if the data are further annotated with reasoning traces, does not encourage the same reasoning behaviors elicited from large-scale RL training on verifiable tasks (Chu et al., 2025). Additionally, naive next-token prediction objective induces training-inference distribution mismatch: during training, the model conditions only on the dataset contexts, whereas at inference, it conditions on self-sampled contexts. Training on self-sampled contexts, as occurs

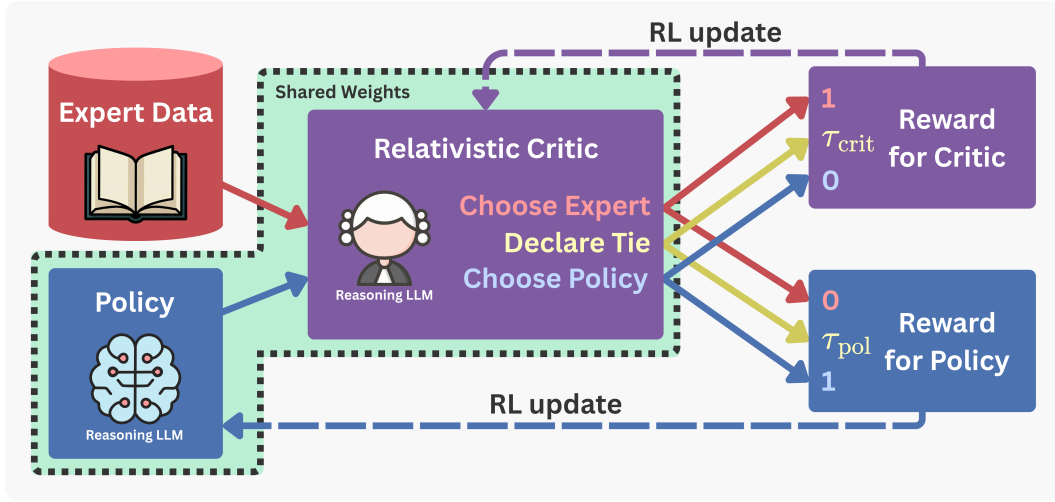


Figure 1: **Overview of RARO.** The method creates an adversarial game between a *policy* and a *relativistic critic* that share the same weights. The critic is rewarded for identifying the experts among (expert, policy) answer pairs, while the policy is rewarded for deceiving the critic. Additionally, the critic can declare *tie*, yielding stable rewards when the it is unsure. Both the policy and the critic are trained jointly and continuously via RL.

during RL, yields lower training-inference mismatch, leading to better performance at test time (Ross et al., 2011). Thus, we hypothesize that leveraging expert demonstrations in conjunction with RL could cultivate robust reasoning abilities, leading to improved performance on downstream tasks and offering a new pathway for developing reasoning capabilities in non-verifiable domains.

To this end, we introduce **RARO** (Relativistic Adversarial Reasoning Optimization), a robust RL algorithm that trains LLMs to reason using only expert demonstrations *without* task-specific verifiers or human preferences.

The key contributions of our work are as follows:

- We propose a novel perspective on training reasoning models via **Inverse Reinforcement Learning** (Ng & Russell, 2000). With this perspective, we develop a principled method, RARO, that enables training reasoning models using demonstration data only.
- We evaluate RARO on a controlled toy reasoning task, **Countdown**, where it not only significantly outperforms SOTA baselines without verification, but it nearly matches the performance of RLVR, demonstrating the effectiveness of RARO on inducing reasoning behaviors.
- Next, we further stress test RARO’s reasoning elicitation capability by scaling it on the general domain of math problems via the **DeepMath** dataset (He et al., 2025), where RARO again outperforms baselines without verification and exhibits similar scaling trends as RLVR, demonstrating the *scalability* of RARO.
- Finally, we demonstrate that RARO’s superior performance generalizes well to non-verifiable domains by evaluating it on **Poetry Writing**, where it substantially outperforms all baselines, underscoring its effectiveness in open-ended tasks without verification.

2 RELATED WORK

2.1 REINFORCEMENT LEARNING WITH VERIFIABLE REWARDS

Chain-of-Thought (CoT) prompting (Wei et al., 2022) is a simple yet effective technique that enables LLMs to generate intermediate reasoning tokens, steering them toward correct answers. This approach has become a central focus for enhancing reasoning, pairing naturally with test-time scaling for further performance gains (Snell et al., 2024).

Currently, the standard method to elicit such strong CoT capabilities is Reinforcement Learning with Verifiable Rewards (RLVR). RLVR methods train LLMs to produce long reasoning traces on tasks with ground-truth verifiers, enabling recent open-source models to achieve expert-level performance (DeepSeek-AI et al., 2025; Yang et al., 2025b).

The dominant algorithm in this space is Group Relative Policy Optimization (GRPO) (Shao et al., 2024), which builds upon Proximal Policy Optimization (PPO) (Schulman et al., 2017) by estimating advantages via group-wise sample averages. Subsequent works like DAPO (Yu et al., 2025) and GSPO (Zheng et al., 2025) have further improved its efficiency and stability. However, while RLVR is highly effective, it is fundamentally constrained to verifiable tasks such as mathematics and competitive programming.

2.2 GENERAL REASONING LEARNING

While RLVR is effective for training LLMs to reason on readily verifiable tasks, it does not directly extend to the broader setting of learning reasoning on real-world domains with no verifiers, yet many of these tasks could still benefit from explicit reasoning (Zhou et al., 2025).

Although no consensus method exists for general reasoning learning to our knowledge, several recent efforts make early progress. Zhou et al. (2025) and Gurung & Lapata (2025) propose to train LLMs to reason with reward derived from the model’s own logits on expert answers rather than from an external verifier. Jia et al. (2025) propose a pairwise generative reward model with a PPO-style objective for non-verifiable writing tasks, achieving gains without external training signals. Gunjal et al. (2025) propose using an LLM-as-judge (Gu et al., 2025) together with pre-generated rubrics from strong LLM to provide rewards for non-verifiable tasks. Ma et al. (2025) distill a model-based verifier from a strong teacher to train general reasoners without rule-based verifiers. Li et al. (2025) investigate large-scale multi-task RLVR, hypothesizing that breadth across many tasks induces stronger general reasoning. We build on this line of work while adopting a demonstration-only setting and a complementary perspective based on Inverse Reinforcement Learning.

2.3 INVERSE REINFORCEMENT LEARNING

Inverse Reinforcement Learning (IRL) (Ng & Russell, 2000) studies the task of recovering a reward function for which an observed expert policy is near-optimal. A seminal application is robust imitation learning, most notably Generative Adversarial Imitation Learning (GAIL) (Ho & Ermon, 2016), casting imitation as an adversarial game between a policy and a discriminator.

Sun & van der Schaar (2025) recently investigated the application of IRL for aligning LLMs with expert demonstrations. They show that a classifier trained in the IRL paradigm can serve as an effective reward model for Best-of-N sampling. However, their work stops short of exploring stable, joint adversarial training, or reasoning-intensive tasks, where the model must learn to navigate complex solution spaces rather than aligning with surface-level preferences.

3 METHOD

We study the general setting where we are given an expert Question–Answer (QA) dataset, and we aim to train a reasoning LLM policy to produce expert-level answers via explicit CoT reasoning. We adopt this setting because verifiable tasks are relatively scarce, whereas expert demonstration data are abundant for many non-verifiable domains (e.g., highly upvoted Stack Exchange answers).

To approach this task, we propose a novel inverse reinforcement learning framework that sets up an adversarial interaction between a *reasoning policy* and a *relativistic critic*: the policy learns to output expert-like answers, while the critic learns to discriminate between policy and expert answers via pairwise comparison. By jointly training both the policy and the critic to reason via RL, we enable the emergence of strong reasoning capabilities from demonstrations alone, without requiring task-specific verifiers.

3.1 REASONING OPTIMIZATION VIA INVERSE REINFORCEMENT LEARNING

Setup. Let $D = \{(q_i, a_i)\}_{i=1}^n$ denote the expert QA dataset. We parameterize our reasoning policy as a *conditional latent-variable model* (Phan et al., 2023) $\pi_\theta(a, z \mid q)$, a distribution over answers a and CoT reasonings z conditioned on a question q . We let \hat{p}_q denote the empirical distribution of questions in D , $\hat{p}_{a|q}$ denote the empirical distribution of expert answers conditioned on a question, and the joint $\hat{p}_D = \hat{p}_{a|q}\hat{p}_q$ denote the empirical distribution of dataset pairs (q, a) .

A natural baseline for producing expert-quality answers is the *maximum likelihood (ML)* objective on expert demonstrations: $\arg \max_\theta \mathbb{E}_{(q,a) \sim \hat{p}_D} [\log \pi_\theta(a \mid q)]$.

However, for models that perform CoT reasoning before producing an answer, each (q, a) is associated with many possible CoT traces. Thus, the marginal likelihood required by the ML objective, $\pi_\theta(a \mid q) = \sum_z \pi_\theta(a, z \mid q)$, involves summing over a combinatorially large (often effectively unbounded) set of traces, rendering exact computation and its gradients computationally impractical.

Inverse Reinforcement Learning. To address this intractability, we adopt the perspective of Inverse Reinforcement Learning (IRL). Rather than maximizing the marginal likelihood directly, we learn a *parameterized reward* $r_\phi(a, q)$ over QA pairs such that optimizing π_θ with respect to r_ϕ yields a “near-optimal” policy that approximately maximizes the ML objective.

We formalize “near-optimality” via the KL-regularized reward-maximization objective. Under this objective, it can be shown (Peng et al., 2019) that the optimal policy has marginal:

$$\pi_{\theta^*(\phi)}(a \mid q) = \frac{1}{Z_{\theta^*(\phi)}(q)} \pi_{\text{ref}}(a \mid q) \exp \left\{ \frac{1}{\beta} r_\phi(a, q) \right\},$$

where $Z_{\theta^*(\phi)}(q)$ is the partition function, π_{ref} is a fixed reference policy, and $\beta > 0$ controls the strength of the KL-regularization. See Appendix A.1 for the full proof.

With a closed-form expression for the optimal marginal under reward model r_ϕ , we have a concrete pathway to optimize ϕ such that $\pi_{\theta^*(\phi)}$ maximizes the ML objective. Specifically, as shown in Appendix A.2, we can directly optimize ϕ via gradient ascent with the following gradient:

$$\nabla_\phi \mathcal{L}(\phi) = \frac{1}{\beta} \left(\underbrace{\mathbb{E}_{(q,a) \sim \hat{p}_D} [\nabla_\phi r_\phi(a, q)]}_{\text{expert answers}} - \underbrace{\mathbb{E}_{q \sim \hat{p}_q} \mathbb{E}_{a' \sim \pi_{\theta^*(\phi)}(\cdot \mid q)} [\nabla_\phi r_\phi(a', q)]}_{\text{policy answers}} \right).$$

Finally, approximating $\pi_{\theta^*(\phi)}$ by optimizing π_θ with reward r_ϕ via RL, we have an algorithm that optimizes reasoning policy π_θ with respect to the ML objective as shown in Algorithm 1.

Algorithm 1 Alternating Policy-Reward Optimization

Inputs: Dataset $D = \{(q_i, a_i)\}$; Batch B ; Learning rates η_r, η_π .

Models: Reward $r_\phi(a, q)$; Reasoning policy $\pi_\theta(a, z \mid q)$.

- 1: Initialize ϕ, θ
- 2: **for** $t = 1, \dots, T$ **do**
- 3: Draw $\{(q_i, a_i^E)\}_{i=1}^B$ with $q_i \sim \hat{p}_q, a_i^E \sim \hat{p}_{a|q}(\cdot \mid q_i)$
- 4: For each $i \in [1..B]$, sample $(z_i, a_i^P) \sim \pi_\theta(\cdot, \cdot \mid q_i)$
- 5: **Reward update:**

$$\phi \leftarrow \phi + \eta_r \cdot \frac{1}{\beta} \left(\frac{1}{B} \sum_{i=1}^B \nabla_\phi r_\phi(a_i^E, q_i) - \frac{1}{B} \sum_{i=1}^B \nabla_\phi r_\phi(a_i^P, q_i) \right)$$

- 6: **Policy update:** KL-regularized GRPO with $r_\phi(a, q)$ as the reward.
 - 7: **end for**
 - 8: **return** θ, ϕ
-

3.2 REASONING CRITIC AS REWARD MODEL

To instantiate this framework, we need to decide on an appropriate architecture for the reward model r_ϕ . Our setting targets difficult QA tasks that benefit from reasoning. Thus, to reliably separate expert from policy answers, we expect the reward model to be at least as capable as the policy.

To this end, we represent r_ϕ with a reasoning *critic* c_ϕ that takes an (q, a) pair and outputs $\ell \in \{\text{expert}, \text{policy}\}$, classifying whether an answer is from the expert or the policy. Specifically, we parametrize r_ϕ as the probability of classifying as *expert* for a (q, a) pair.

Under this parameterization, as shown in Appendix A.3, the gradient $\nabla_\phi L$ corresponds to the standard *policy gradient*, resulting in simple reward functions for the critic and policy.

Reward for Critic:

$$R_{\text{critic}}(\ell, a, q) = \mathbb{1}_{\ell \text{ is correct}}$$

Reward for Policy:

$$R_{\text{policy}}(a, q) = \mathbb{1}_{\ell=\text{expert}}, \quad \ell \sim c_\phi(\cdot \mid a, q)$$

This allows us to optimize both the critic and policy using GRPO.

Such reward formulation creates an *adversarial game* between the critic and policy: the critic is rewarded when it correctly classifies answer as coming from the expert or policy, while the policy is rewarded when the critic *incorrectly* classifies its answer as an expert answer.

3.3 RELATIVISTIC CRITIC: THE PAIRWISE ADVANTAGE

Despite the theoretical soundness, the previous setup poses challenges for critic learning. As policy approaches the expert, the classification task becomes much more difficult due to a lack of reference answer for the critic to compare against. In addition, with an optimal policy, the critic effectively degenerates to random guessing, providing high-variance, uninformative gradients to the policy, leading to training instability as we observed (see Appendix D.2).

To address these limitations, we instead adopt a *relativistic* formulation: the critic takes a triplet (q, a, a^*) consisting of one policy answer and one expert answer, and outputs which is better or `tie` if they are equal in quality. This resolves the degeneracy where the critic is forced to differentiate even when the policy is optimal. We empirically show that the `tie` option is crucial for better performance (see Appendix D.2).

Formally, the *relativistic critic* c_ϕ takes a question q and two candidate answers $(a^{(1)}, a^{(2)})$ and returns a label $\ell \in \{1, 2, \text{tie}\}$. Assuming one expert and one policy answer, we can define:

Reward for Critic:

$$R_{\text{critic}}(q, a^{(1)}, a^{(2)}) = \mathbb{1}_{\ell \text{ is expert}} + \tau_{\text{crit}} \cdot \mathbb{1}_{\ell=\text{tie}}, \quad \tau_{\text{crit}} \in [0, 1].$$

Reward for Policy:

$$R_{\text{policy}}(q, a^{(1)}, a^{(2)}) = \mathbb{1}_{\ell \text{ is policy}} + \tau_{\text{pol}} \cdot \mathbb{1}_{\ell=\text{tie}}, \quad \tau_{\text{pol}} \in [0, 1].$$

where τ_{crit} and τ_{pol} are *tie rewards*, new hyperparameters introduced to handle the `tie` label.

Unlike the binary classification setup, the relativistic critic is now given a *pairwise comparison* task: the critic is rewarded when it correctly identifies the expert answer, and the policy is rewarded when the critic mistakenly identifies its answer as the expert answer, with additional `tie` rewards to ensure non-degeneracy and stable learning.

3.4 RARO: RELATIVISTIC ADVERSARIAL REASONING OPTIMIZATION

Finally, we identify the key techniques for stable and efficient training. First, we use a *shared LLM* for both the critic and the policy, which reduces memory usage and promotes generalization. This allows us to employ *data mixing*, where policy and critic rollouts are combined in a single batch,

simplifying the training loop. To prevent the critic from catastrophic forgetting, we sample critic prompts from a *replay buffer* that stores all past expert and policy answers. Finally, we incorporate several practical improvements to the GRPO algorithm, such as over-length filtering and removing advantage/length normalization. For full implementation details, please refer to Appendix C.1.

Incorporating all of these optimizations into a concrete algorithm, we arrive at our final algorithm, *RARO (Relativistic Adversarial Reasoning Optimization)*, shown in Algorithm 2.

Algorithm 2 RARO (Relativistic Adversarial Reasoning Optimization)

Inputs: Dataset $D = \{(q_i, a_i)\}$; Tie reward $\tau_{\text{pol}}, \tau_{\text{crit}}$; Loss weight $\lambda_{\text{pol}}, \lambda_{\text{crit}}$; Batch B ; Rollout K .
Model: Shared $\theta \rightarrow \pi_\theta, c_\theta$. Replay buffer \mathcal{R} .

```

1: Initialize  $\theta, \mathcal{R} \leftarrow \emptyset$ ;
2: for  $t = 1, \dots, T$  do
3:    $\mathcal{R}_{\text{new}} \leftarrow \emptyset$ 
4:   Draw  $\{(q_i, a_i^{\text{E}})\}_{i=1}^B \sim D$ 
5:   for  $i = 1 \dots B, k = 1 \dots K$  do
6:      $(z_{i,k}^{\text{P}}, a_{i,k}^{\text{P}}) \sim \pi_\theta(\cdot | q_i)$ ; build pair  $(a_i^{\text{E}}, a_{i,k}^{\text{P}})$ 
7:      $\ell_{i,k} \sim c_\theta(\cdot | q_i, a_i^{\text{E}}, a_{i,k}^{\text{P}})$ 
8:      $R_{i,k}^{\text{pol}} \leftarrow \mathbb{1}_{\ell_{i,k} \text{ is policy}} + \tau_{\text{pol}} \mathbb{1}_{\ell_{i,k} = \text{tie}}$ 
9:      $\mathcal{R}_{\text{new}} \leftarrow \mathcal{R}_{\text{new}} \cup \{(q_i, a_i^{\text{E}}, a_{i,k}^{\text{P}})\}$ 
10:   end for
11:    $\mathcal{C} \leftarrow \text{Mix}(\mathcal{R}_{\text{new}}, \mathcal{R})$ 
12:    $\mathcal{R} \leftarrow \mathcal{R} \cup \mathcal{R}_{\text{new}}$ 
13:   for  $(q_j, a_j^{\text{E}}, a_j^{\text{P}}) \in \mathcal{C}$  do
14:      $\ell_j \sim c_\theta(\cdot | q_j, a_j^{\text{E}}, a_j^{\text{P}})$ 
15:      $R_j^{\text{crit}} \leftarrow \mathbb{1}_{\ell_j \text{ is expert}} + \tau_{\text{crit}} \mathbb{1}_{\ell_j = \text{tie}}$ 
16:   end for
17:   GRPO step on  $\theta$  to maximize:  $\lambda_{\text{pol}} J_{\text{pol}}(\theta) + \lambda_{\text{crit}} J_{\text{crit}}(\theta) - \beta D_{\text{KL}}(\pi_\theta \| \pi_{\text{ref}})$ 
18: end for
19: return  $\theta$ 

```

} **Policy rollouts**

} **Critic rollouts**

4 EXPERIMENTAL SETUP

4.1 TASKS & DATASETS

We evaluate RARO on three diverse reasoning tasks that probe complementary aspects of reasoning. See Appendix C.2 for more details on the datasets.

Countdown. First, we evaluate our method on the Countdown task, a controlled toy reasoning task where answer verification is much simpler than answer generation. We use a 24-style variant where the goal is to combine four integers to obtain 24 (see Appendix C.2 for details). Through this task, we aim to study the effectiveness of our method on reasoning capabilities in a controlled environment where answer checking is much easier than solution search.

DeepMath. Then, we evaluate our method on the domain of general math reasoning problems using the DeepMath dataset (He et al., 2025). Compared to Countdown, answer verification in the general math domain is significantly more challenging, often requiring solving the problem from scratch. Through this task, we aim to stress test our method on difficult reasoning environments where verification is as difficult as generation.

Poetry Writing. Finally, we extend our method to its intended setting of non-verifiable, open-ended reasoning tasks. While there exists benchmarks for non-verifiable domains (Arora et al.,

2025; Paech, 2024), there is no official training data associated with them. Thus, we choose to evaluate our method and baselines on a custom Poetry Writing dataset. Unlike the math tasks, poetry writing does not admit an objective verifier. Thus, for evaluation, we use GPT-5 (OpenAI, 2025) as a judge to evaluate poems in both isolation and in comparison to the expert poem (see Appendix C.2 for details). This task represents the non-verifiable regime that our method aims to handle, where explicit reasoning could significantly improve quality.

4.2 BASELINES

We compare RARO against several strong post-training baselines under the same dataset, training, and evaluation setup.

Supervised Fine-Tuning (SFT). The SFT baseline trains the base models to directly maximize the conditional log-likelihood of the expert answer given the question, representing the standard use of demonstration data.

Rationalization. Following prior work on self-rationalizing techniques (Zelikman et al., 2022), we construct a rationalization baseline that augments each expert answer with an explicit CoT. Concretely, we prompt the base model to annotate the expert demonstrations with free-form *rationale*, then perform SFT on the concatenated (question, rationale, answer) sequences. This baseline attempts to incentivize the base model to learn to reason before producing the final answer.

Iterative Direct Preference Optimization (DPO). A natural way to match the policy’s output distribution to the expert is to apply Iterative DPO (Rafailov et al., 2024). Inspired by Iterative Reasoning Preference Optimization (Pang et al., 2024), we perform 3 rounds of DPO iteratively: in each round, we sample one response per question to form preference pairs favoring the expert. We initialize from the SFT checkpoint to mitigate distribution mismatch and report the best performance across rounds.

RL from logit-based reward (RL-Logit). Recent work has proposed training reasoning LLMs via RL where the reward is derived from the model’s own logits on expert answers rather than from an external verifier (Zhou et al., 2025; Gurung & Lapata, 2025). We implement two variants of such *logit-based* rewards (see Appendix C.3 for details):

- a *log-probability reward*, which uses the log-probability of the expert answer a^* given the question q and generated reasoning tokens z as the scalar reward $\log \pi_\theta(a^* | q, z)$; and
- a *perplexity reward*, which instead maximizes the negative perplexity of the expert answer under the same conditional distribution.

In our evaluation, we report the metrics from the best performing variant.

RL with Verifiable Reward (RLVR). For Countdown and DeepMath, where ground-truth verifiers are available, we additionally include a RLVR baseline trained with GRPO on binary rewards given by the verifier. This corresponds to the standard RLVR setting, and serves as an upper-bound for our method on tasks where verification is accessible.

4.3 TRAINING & EVALUATION SETUP

We evaluate our method and baselines on the Qwen2.5 (Qwen et al., 2025) family of models, and to focus on improving reasoning performance rather than language understanding, we initialize from the instruction-tuned checkpoints instead of the pretrained model checkpoints. We select the Qwen2.5 family because they are popular *non-reasoning* LLMs, allowing us to study the effectiveness of our method on eliciting reasoning behaviors in a controlled manner.

Countdown and DeepMath are evaluated with a ground-truth verifier, while Poetry Writing is evaluated with GPT-5 as a judge in two fashions: a *scalar score* normalized from 1-7 to 0-100 and a *win-rate* against the expert poem. For both fashions, we prompt GPT-5 to focus its evaluations on prompt adherence and literary qualities. See Appendix C.2 for further details.

Each dataset is split into train, validation, and test sets, and for each method, we select the non-initial checkpoint with the highest validation performance. We match dataset splits, rollout budgets, hyperparameters, and sampling configurations for all methods when possible to ensure a fair comparison. Unless otherwise specified, all methods are trained and evaluated with a reasoning budget of 2048 tokens. Full implementation details and hyperparameters are provided in Appendix C.

5 MAIN RESULTS

We present our experimental results structured by task: Countdown, DeepMath, and Poetry Writing. Across these domains, we observe that our method significantly and consistently outperforms all baselines, scaling effectively with both reasoning budget and model size.

5.1 COUNTDOWN

We first evaluate RARO on the Countdown task, a controlled toy reasoning task where answer verification is much simpler than answer generation. For this task, we focus our investigation at the 1.5B model size and further ablate our method and baselines with respect to both the training and test-time reasoning token budget. We do not ablate along model size as Countdown is a straightforward task where the reasoning budget is the primary bottleneck rather than model capacity (see Appendix D.1 for additional details).

Superior Performance at Fixed Budget. At a fixed reasoning budget of 2048 tokens, RARO achieves 54.4% accuracy, significantly outperforming the best verifier-free baseline (SFT, 40.7%) by 13.7% and nearly matching the oracle RLVR baseline (57.7%) (Table 1). We also notice that RL-Logit (2.2%) and Rationalization (12.5%) perform rather poorly, and we hypothesize that it is likely due to the base model’s inability to produce high-quality rationalizations or informative logits. The strong performance of RARO demonstrates that our learned critic provides a signal comparable to verification rewards.

Emergence of Self-Correcting Search. A key qualitative finding is the emergence of explicit search behaviors. As shown in Figure 5, our model learns to explore the solution space dynamically proposing combinations, verifying them, and backtracking when they are incorrect (e.g., “too high”). This self-correction mechanism acts as an internal verifier, allowing the model to recover from errors. Such behavior is absent in the SFT baseline, as it is trained to directly output a candidate answer without any explicit reasoning.

Scaling with Reasoning Budget. Finally, we examine the scalability of RARO with respect to both training and test-time reasoning token budget. Figure 2 illustrates a clear trend: while the SFT baseline’s performance plateaus at 40.7% regardless of the token budget, our method exhibits continuous improvement as the budget increases, rising from 33.1% at 256 tokens to 61.3% at 4096 tokens. Notably, the result at 4096 tokens is achieved by a model trained with a 2048-token budget, demonstrating that our method can extrapolate to longer reasoning chains at test time without additional training. This scaling behavior confirms that RARO successfully transforms reasoning budget into better performance, a hallmark of effective reasoning.

Method	Countdown accuracy (%) \uparrow
RLVR (<i>with verifier</i>)	57.7 ± 1.6
Base	2.0 ± 0.4
SFT	40.7 ± 1.6
Rationalization	12.5 ± 1.0
Iterative DPO	40.4 ± 1.5
RL-Logit	2.2 ± 0.4
RARO	54.4 ± 1.5

Table 1: **Main Countdown Results.** RARO against baselines at a fixed reasoning budget of 2048 tokens.

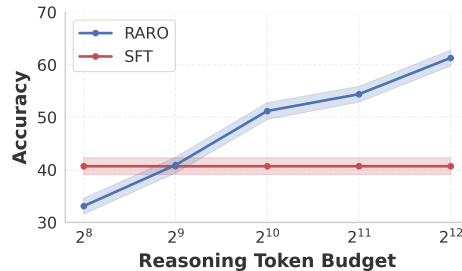


Table 2: **Reasoning Budget Scaling on Countdown.** Our method scales effectively with both training and test-time token budget, unlike SFT (best baseline). See Table 8 in Appendix E for detailed data.

5.2 DEEPMATH

Next, we evaluate RARO on the DeepMath dataset, a collection of general math problems. For the DeepMath task, we focus on scaling our method and baselines with respect to model size instead of reasoning budget, as it is a much more difficult setting where model capacity is a real bottleneck in performance.

Method	DeepMath accuracy (%) \uparrow	Poetry score (0-100) \uparrow	Poetry win-rate (%) \uparrow (vs. <i>expert</i>)
1.5B			
RLVR (<i>with verifier</i>)	50.9 ± 1.9	N/A	N/A
Base	29.6 ± 1.9	35.0 ± 0.9	0.0 ± 0.0
SFT	35.7 ± 1.8	53.7 ± 1.0	2.3 ± 1.0
Rationalization	34.5 ± 2.0	35.6 ± 1.6	0.8 ± 0.5
Iterative DPO	33.0 ± 1.9	48.6 ± 0.9	0.0 ± 0.0
RL-Logit	37.7 ± 1.9	36.4 ± 0.7	0.0 ± 0.0
RARO	41.3 ± 1.9	67.8 ± 0.8	7.8 ± 1.7
3B			
RLVR (<i>with verifier</i>)	55.8 ± 2.0	N/A	N/A
Base	39.4 ± 1.9	46.5 ± 0.9	0.0 ± 0.0
SFT	39.0 ± 1.9	57.4 ± 1.0	2.3 ± 1.0
Rationalization	32.3 ± 1.9	30.8 ± 1.9	0.4 ± 0.4
Iterative DPO	34.2 ± 1.9	69.8 ± 0.8	6.6 ± 1.5
RL-Logit	43.1 ± 2.0	46.9 ± 0.8	0.4 ± 0.4
RARO	49.1 ± 1.9	71.9 ± 0.8	17.2 ± 2.4
7B			
RLVR (<i>with verifier</i>)	66.2 ± 1.9	N/A	N/A
Base	44.2 ± 2.1	54.0 ± 0.9	1.2 ± 0.7
SFT	42.3 ± 1.9	65.4 ± 1.0	5.9 ± 1.4
Rationalization	48.6 ± 1.9	57.7 ± 1.2	5.1 ± 1.3
Iterative DPO	36.9 ± 2.0	66.5 ± 0.9	5.1 ± 1.4
RL-Logit	49.3 ± 2.0	55.4 ± 0.8	3.9 ± 1.2
RARO	57.5 ± 2.0	77.3 ± 0.8	25.0 ± 2.6

Table 3: **Main results for DeepMath and Poetry.** We report results for RARO against baselines on DeepMath and Poetry Writing across model scales with a reasoning budget of 2048 tokens. For Iterative DPO, we report the max of the 3 rounds. For RL-Logit, we report the best over the 2 variants. See Table 13 in Appendix E for full data.

Significant Improvement over Baselines. As reported in Table 3, RARO consistently outperforms all verifier-free baselines across model scales. With the 1.5B model, we achieve 41.3% accuracy compared to 37.7% for the best baseline (RL-Logit), an improvement of 3.6%. This advantage grows with model size: at 3B, our method (49.1%) surpasses the best baseline (RL-Logit, 43.1%) by 6.0%, and at 7B, it reaches 57.5%, beating it by 8.2%. These results demonstrate that our adversarial learning framework provides a strong signal for reasoning that outperforms not only purely supervised approaches like SFT or Rationalization but also RL-Logit.

Stable Training Dynamics. We further analyze the training dynamics of RARO on DeepMath. As shown in Figure 3 and further in Appendix B, our coupled training objective maintains a robust equilibrium, allowing the policy to steadily improve its reasoning capabilities and response length without collapsing. This stability confirms the robustness of our optimization procedure.

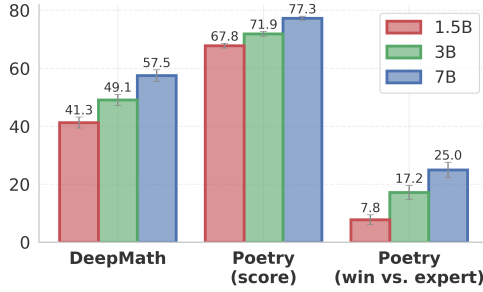


Figure 2: **Performance scaling.** RARO consistently improves with model size (1.5B to 7B) across both DeepMath and Poetry Writing.

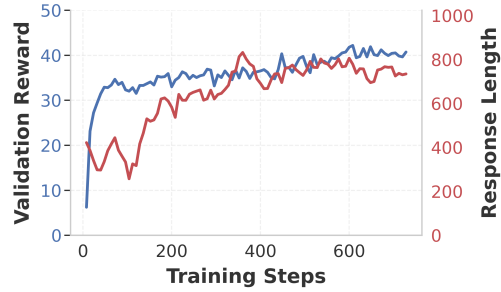


Figure 3: **Stable Reward and Length Growth.** The validation reward and response length of RARO on DeepMath (1.5B) continuously grows over time, indicating a stable dynamic.

Effective Test-Time Scaling. Another key advantage of RARO is that our learned critic enables natural Test-Time Scaling (TTS) to further improve the policy’s performance. Specifically, our critic’s pairwise comparison setup allows for a *single-elimination tournament* with the critic as the judge (see Algorithm 3), enabling further policy improvements with additional rollouts. As shown in Figure 4 (and detailed in Table 9), increasing the number of rollouts from 1 to 16 consistently improves performance. Notably, with 16 rollouts, RARO achieves 53.6% on the 1.5B model and 57.9% on the 3B model. When comparing against the RLVR baseline with the same TTS strategy (Table 10), we observe that RARO achieves a similar rate of improvement. This result highlights that RARO, when combined with test-time search, can scale effectively, matching the scaling trends of models trained with oracle verifiers.

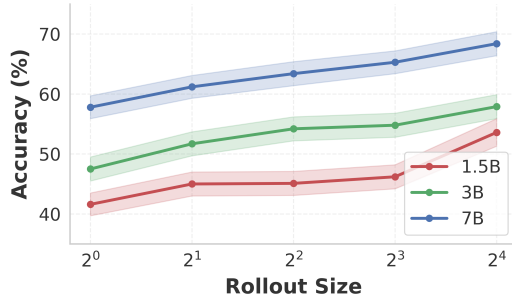


Figure 4: **Test-time Scaling (TTS) on DeepMath.** Performance improves as the number of rollouts (N) increases for all model sizes. See Table 9 in Appendix E for detailed data.

5.3 POETRY WRITING

Finally, we study RARO on Poetry Writing, an open-ended, un-verifiable domain that benefits from specialized reasoning capabilities. For this task, similar to DeepMath, we study RARO across a range of model sizes.

Surpassing Supervised Baselines. Table 13 reveals a striking performance gap between RARO and baselines. While SFT and Rationalization achieve modest win-rates against expert poetry (peaking at 5.9% with the 7B model), RARO reaches 25.0%, a four-fold improvement. This advantage is also reflected in the scoring evaluation, where RARO consistently surpasses baselines (e.g., 67.8 vs. 53.7 for SFT at 1.5B). Notably, RL-Logit, leading baseline for DeepMath, fails to produce competitive results, yielding near-zero improvement over the base model (36.4 vs. 35.0 at 1.5B) for both the win-rate and scoring evaluation.

Scaling Creative Capabilities. A key result is the scalability of RARO with model size in the creative domain. As we increase model capacity from 1.5B to 7B, the win-rate against expert human poems grows substantially, from 7.8% to 25.0%. The scoring evaluation similarly improves from 67.8 to 77.3. This trend shows that just like verifiable domains, RARO continues to effectively scale with model size in open-ended domains.

Emergent Qualitative Reasoning. Qualitatively, RARO induces explicit planning and reasoning behaviors. As shown in Figure 5, the model learns to decompose complex problems into structured

Countdown Use the four numbers 19, 11, 48, and 6 to create an expression that equals 24.	DeepMath Find the equation of the normal line to the curve $(x^2 + y^2)^{3/2} = 2xy$ at the point $(\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}})$.	Poetry Writing a poem about a child's fragmented memory of a father leaving, told in intimate, sensory free verse
RARO Policy To find an expression using the four numbers 19, 11, 48, and 6 that equals 24, let's try different combinations. 1. $(48 - 11) * (19 - 6) = 37 * 13 = 481$ (too high) 2. $(48 - 19) * (11 - 6) = 29 * 5 = 145$ (too high) ... 20. $48 / (19 - (11 + 6)) = 48 / (19 - 17) = 48 / 2 = 24$ (correct) <hr/> Answer: $48 / (19 - (11 + 6))$	RARO Policy To find the equation of the normal line to the curve $(x^2 + y^2)^{3/2} = 2xy$ at the point $(\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}})$, we need to follow these steps: 1. Differentiate the curve implicitly to find the slope of the tangent line at the given point. 2. Use the slope of the tangent line to find the slope of the normal line. 3. Write the equation of the normal line using the point-slope form. <hr/> Let's start with... <hr/> Answer: $y = x$	RARO Policy To create such a poem, I'd: 1. Focus on sensory details that might linger in a child's memory. ... 4. Incorporate physical and emotional sensations that capture the essence of the scene. <hr/> Answer: One Memory of My Father Leaving There was the sound of a suitcase rolling on the hallway carpet; ... or a man thinking and trying not to cry.

Figure 5: **Qualitative examples for Countdown (1.5B), DeepMath (7B), and Poetry Writing (7B).** For each task, we show the input (top) and the truncated reasoning and answer sampled from policies trained with RARO (bottom). See Appendix E for full examples as well as example critic inputs and outputs.

plans. Specifically, in Poetry Writing, it decomposes the prompt into key themes (e.g., “sensory details”, “fragmented memory”) and stylistic constraints (e.g., “free verse”, “unrhymed, natural cadences”) before generating the poem. This demonstrates that RARO effectively elicits reasonings that align the model’s output to the task requirements.

6 CONCLUSION & FUTURE WORK

We introduced RARO (Relativistic Adversarial Reasoning Optimization), a novel approach to training reasoning LLMs using only expert demonstrations, thereby bypassing the need for task-specific verifiers or expensive preference annotations. By formulating the problem as Inverse Reinforcement Learning and incorporating a relativistic critic setup, we obtain a principled and stable adversarial training algorithm that yields strong reasoning capabilities.

Our experiments demonstrate the effectiveness of RARO: (i) on the controlled Countdown task, it not only outperforms verifier-free baselines but also nearly matches the performance of RLVR; (ii) on the general math domain, it exhibits similar desirable scalability trends to RLVR while outperforming baselines without verification; and (iii) on the open-ended Poetry Writing task, it successfully elicits emerging specialized reasoning capabilities and significantly surpasses all baselines. Together, these findings suggest that RARO is a promising and practical approach for training reasoning models without reliance on explicit verifiers.

Future work includes: (i) extending the framework to more generalized adversarial setups that stabilize training across diverse domains; (ii) improving sample efficiency; (iii) scaling the method to larger, state-of-the-art model sizes; and (iv) developing an alternative critic setup that enables better reward interpretability. See Appendix B for more details.

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A DERIVATIONS

A.1 DERIVATION OF CLOSED-FORM OPTIMAL POLICY

Proposition A.1. *Consider the KL-regularized reward-maximization objective:*

$$\theta^*(\phi) = \arg \max_{\theta} \mathbb{E}_{(q,a) \sim \hat{p}_D} \left[r_{\phi}(a, q) - \beta D_{\text{KL}}(\pi_{\theta}(\cdot | q) \| \pi_{\text{ref}}(\cdot | q)) \right].$$

The optimal policy has the following closed-form solution:

$$\pi_{\theta^*(\phi)}(a | q) = \frac{1}{Z_{\theta^*(\phi)}(q)} \pi_{\text{ref}}(a | q) \exp \left\{ \frac{1}{\beta} r_{\phi}(a, q) \right\},$$

where $Z_{\theta^*(\phi)}(q)$ is the partition function ensuring normalization.

Proof. We derive the closed-form solution for the KL-regularized reward maximization objective. Consider the objective function for a single question q :

$$\mathcal{J}(\pi) = \mathbb{E}_{a \sim \pi(\cdot | q)} [r_{\phi}(a, q)] - \beta D_{\text{KL}}(\pi(\cdot | q) \| \pi_{\text{ref}}(\cdot | q)). \quad (1)$$

Expanding the KL divergence term:

$$\begin{aligned} D_{\text{KL}}(\pi \| \pi_{\text{ref}}) &= \mathbb{E}_{a \sim \pi(\cdot | q)} \left[\log \frac{\pi(a | q)}{\pi_{\text{ref}}(a | q)} \right] \\ &= \mathbb{E}_{a \sim \pi(\cdot | q)} [\log \pi(a | q) - \log \pi_{\text{ref}}(a | q)]. \end{aligned}$$

Substituting this back into the objective:

$$\begin{aligned} \mathcal{J}(\pi) &= \mathbb{E}_{a \sim \pi(\cdot | q)} [r_{\phi}(a, q) - \beta \log \pi(a | q) + \beta \log \pi_{\text{ref}}(a | q)] \\ &= \beta \mathbb{E}_{a \sim \pi(\cdot | q)} \left[\frac{1}{\beta} r_{\phi}(a, q) + \log \pi_{\text{ref}}(a | q) - \log \pi(a | q) \right] \\ &= -\beta \mathbb{E}_{a \sim \pi(\cdot | q)} \left[\log \pi(a | q) - \left(\log \pi_{\text{ref}}(a | q) + \frac{1}{\beta} r_{\phi}(a, q) \right) \right]. \end{aligned}$$

Let us define the normalized Gibbs distribution:

$$\pi^*(a | q) = \frac{1}{Z(q)} \pi_{\text{ref}}(a | q) \exp \left(\frac{1}{\beta} r_{\phi}(a, q) \right), \quad (2)$$

where $Z(q) = \int \pi_{\text{ref}}(a' | q) \exp \left(\frac{1}{\beta} r_{\phi}(a', q) \right) da'$ is the partition function. Taking the logarithm of π^* :

$$\log \pi^*(a | q) = \log \pi_{\text{ref}}(a | q) + \frac{1}{\beta} r_{\phi}(a, q) - \log Z(q). \quad (3)$$

Substituting $\log \pi_{\text{ref}}(a | q) + \frac{1}{\beta} r_{\phi}(a, q) = \log \pi^*(a | q) + \log Z(q)$ into the objective:

$$\begin{aligned} \mathcal{J}(\pi) &= -\beta \mathbb{E}_{a \sim \pi(\cdot | q)} [\log \pi(a | q) - (\log \pi^*(a | q) + \log Z(q))] \\ &= -\beta \left(\mathbb{E}_{a \sim \pi(\cdot | q)} \left[\log \frac{\pi(a | q)}{\pi^*(a | q)} \right] - \log Z(q) \right) \\ &= -\beta D_{\text{KL}}(\pi \| \pi^*) + \beta \log Z(q). \end{aligned}$$

Since $\beta > 0$ and $\log Z(q)$ does not depend on π , maximizing $\mathcal{J}(\pi)$ is equivalent to minimizing the KL divergence $D_{\text{KL}}(\pi \| \pi^*)$. By Gibbs' inequality, $D_{\text{KL}}(\pi \| \pi^*) \geq 0$, with equality if and only if $\pi = \pi^*$ almost everywhere. Thus, the optimal policy is given by:

$$\pi_{\theta^*(\phi)}(a | q) = \pi^*(a | q) = \frac{1}{Z(q)} \pi_{\text{ref}}(a | q) \exp \left(\frac{1}{\beta} r_{\phi}(a, q) \right). \quad (4)$$

□

A.2 PROOF OF REWARD GRADIENT

Proposition A.2. *Using the closed-form policy, the gradient of the maximum likelihood objective $\mathcal{L}(\phi) = \mathbb{E}_{(q,a) \sim \hat{p}_D} [\log \pi_{\theta^*(\phi)}(a | q)]$ with respect to ϕ is:*

$$\nabla_{\phi} \mathcal{L}(\phi) = \frac{1}{\beta} \left(\mathbb{E}_{(q,a) \sim \hat{p}_D} [\nabla_{\phi} r_{\phi}(a, q)] - \mathbb{E}_{q \sim \hat{p}_q} \mathbb{E}_{a' \sim \pi_{\theta^*(\phi)}(\cdot | q)} [\nabla_{\phi} r_{\phi}(a', q)] \right).$$

Proof. We aim to derive the gradient of the data log-likelihood objective with respect to the reward parameters ϕ . Recall the objective:

$$\mathcal{L}(\phi) = \mathbb{E}_{(q,a) \sim \hat{p}_D} [\log \pi_{\theta^*(\phi)}(a | q)]. \quad (5)$$

The optimal policy $\pi_{\theta^*(\phi)}$ takes the closed-form solution:

$$\pi_{\theta^*(\phi)}(a | q) = \frac{1}{Z_{\theta^*(\phi)}(q)} \pi_{\text{ref}}(a | q) \exp \left(\frac{1}{\beta} r_{\phi}(a, q) \right), \quad (6)$$

where $Z_{\theta^*(\phi)}(q) = \int \pi_{\text{ref}}(a' | q) \exp \left(\frac{1}{\beta} r_{\phi}(a', q) \right) da'$ is the partition function.

Substituting the policy expression into the log-likelihood:

$$\begin{aligned} \log \pi_{\theta^*(\phi)}(a | q) &= \log \left(\frac{\pi_{\text{ref}}(a | q) \exp \left(\frac{1}{\beta} r_{\phi}(a, q) \right)}{Z_{\theta^*(\phi)}(q)} \right) \\ &= \log \pi_{\text{ref}}(a | q) + \frac{1}{\beta} r_{\phi}(a, q) - \log Z_{\theta^*(\phi)}(q). \end{aligned}$$

Since π_{ref} does not depend on ϕ , the gradient is:

$$\begin{aligned} \nabla_{\phi} \log \pi_{\theta^*(\phi)}(a | q) &= \nabla_{\phi} \left(\frac{1}{\beta} r_{\phi}(a, q) - \log Z_{\theta^*(\phi)}(q) \right) \\ &= \frac{1}{\beta} \nabla_{\phi} r_{\phi}(a, q) - \frac{\nabla_{\phi} Z_{\theta^*(\phi)}(q)}{Z_{\theta^*(\phi)}(q)}. \end{aligned}$$

We now compute the gradient of the partition function $Z_{\theta^*(\phi)}(q)$ using the Leibniz integral rule (interchanging gradient and integral):

$$\begin{aligned} \nabla_{\phi} Z_{\theta^*(\phi)}(q) &= \nabla_{\phi} \int \pi_{\text{ref}}(a' | q) \exp \left(\frac{1}{\beta} r_{\phi}(a', q) \right) da' \\ &= \int \pi_{\text{ref}}(a' | q) \nabla_{\phi} \exp \left(\frac{1}{\beta} r_{\phi}(a', q) \right) da' \\ &= \int \pi_{\text{ref}}(a' | q) \exp \left(\frac{1}{\beta} r_{\phi}(a', q) \right) \left(\frac{1}{\beta} \nabla_{\phi} r_{\phi}(a', q) \right) da'. \end{aligned}$$

Substituting this back into the gradient term for $\log Z_{\theta^*(\phi)}(q)$:

$$\begin{aligned} \frac{\nabla_{\phi} Z_{\theta^*(\phi)}(q)}{Z_{\theta^*(\phi)}(q)} &= \int \frac{\pi_{\text{ref}}(a' | q) \exp \left(\frac{1}{\beta} r_{\phi}(a', q) \right)}{Z_{\theta^*(\phi)}(q)} \left(\frac{1}{\beta} \nabla_{\phi} r_{\phi}(a', q) \right) da' \\ &= \int \pi_{\theta^*(\phi)}(a' | q) \left(\frac{1}{\beta} \nabla_{\phi} r_{\phi}(a', q) \right) da' \\ &= \mathbb{E}_{a' \sim \pi_{\theta^*(\phi)}(\cdot | q)} \left[\frac{1}{\beta} \nabla_{\phi} r_{\phi}(a', q) \right]. \end{aligned}$$

Finally, averaging over the dataset $(q, a) \sim \hat{p}_D$:

$$\begin{aligned} \nabla_{\phi} \mathcal{L}(\phi) &= \mathbb{E}_{(q,a) \sim \hat{p}_D} \left[\frac{1}{\beta} \nabla_{\phi} r_{\phi}(a, q) - \mathbb{E}_{a' \sim \pi_{\theta^*(\phi)}(\cdot | q)} \left[\frac{1}{\beta} \nabla_{\phi} r_{\phi}(a', q) \right] \right] \\ &= \frac{1}{\beta} \left(\mathbb{E}_{(q,a) \sim \hat{p}_D} [\nabla_{\phi} r_{\phi}(a, q)] - \mathbb{E}_{q \sim \hat{p}_q} \mathbb{E}_{a' \sim \pi_{\theta^*(\phi)}(\cdot | q)} [\nabla_{\phi} r_{\phi}(a', q)] \right). \end{aligned}$$

This completes the derivation. \square

A.3 DERIVATION OF REASONING REWARD GRADIENT

Proposition A.3. *Let the reward be parameterized by a critic $c_\phi(\ell \mid a, q)$ with labels $\ell \in \{\text{expert}, \text{policy}\}$ as $r_\phi(a, q) = c_\phi(\ell = \text{expert} \mid a, q)$. The gradient of the loss with respect to critic parameters ϕ is:*

$$\nabla_\phi L = \frac{1}{\beta} \mathbb{E}_{q \sim \hat{p}_q(\cdot)} \left[\mathbb{E}_{a \sim \hat{p}_{a|q}(\cdot|q) \cup \pi_\theta(a|q)} \left[\mathbb{E}_{\ell \sim c_\phi(\cdot|a, q)} \left[R(\ell, a, q) \nabla_\phi \log c_\phi(\ell \mid a, q) \right] \right] \right],$$

where

$$R(\ell, a, q) = \mathbb{1}_{\ell \text{ is correct}}$$

Proof. In this section, we derive the specific form of the reward gradient when the reward is parameterized by a critic LLM c_ϕ . Recall from Eq. (A.2) that the gradient of the loss is:

$$\nabla_\phi \mathcal{L}(\phi) = \frac{1}{\beta} \left(\mathbb{E}_{(q, a) \sim \hat{p}_D} [\nabla_\phi r_\phi(a, q)] - \mathbb{E}_{q \sim \hat{p}_q} \mathbb{E}_{a' \sim \pi_\theta(\cdot|q)} [\nabla_\phi r_\phi(a', q)] \right),$$

where we have approximated the optimal policy $\pi_{\theta^*}(\phi)$ with the current policy π_θ .

We parameterize the reward using the probability of the answer being expert-generated, as predicted by a binary classifier (critic) $c_\phi(\ell \mid a, q)$ where $\ell \in \{\text{expert}, \text{policy}\}$:

$$r_\phi(a, q) = c_\phi(\ell = \text{expert} \mid a, q).$$

Let $p_E = c_\phi(\ell = \text{expert} \mid a, q)$ and $p_P = c_\phi(\ell = \text{policy} \mid a, q) = 1 - p_E$. The gradient of the reward with respect to ϕ is:

$$\nabla_\phi r_\phi(a, q) = \nabla_\phi p_E.$$

We can express this gradient using the REINFORCE trick (log-derivative trick) over the binary outcome ℓ . Consider the quantity:

$$\begin{aligned} \mathbb{E}_{\ell \sim c_\phi(\cdot|a, q)} [\mathbb{1}_{\ell=\text{expert}} \nabla_\phi \log c_\phi(\ell \mid a, q)] &= \mathbb{1}_{\text{expert}=\text{expert}} p_E \nabla_\phi \log p_E + \mathbb{1}_{\text{policy}=\text{expert}} p_P \nabla_\phi \log p_P \\ &= 1 \cdot \nabla_\phi p_E + 0 \\ &= \nabla_\phi p_E. \end{aligned}$$

Thus, we have the identity:

$$\nabla_\phi r_\phi(a, q) = \mathbb{E}_{\ell \sim c_\phi(\cdot|a, q)} [\mathbb{1}_{\ell=\text{expert}} \nabla_\phi \log c_\phi(\ell \mid a, q)].$$

Substituting this identity back into the loss gradient expression:

1. Expert Term ($(q, a) \sim \hat{p}_D$): The answers come from the expert distribution, so the correct label is expert.

$$\mathbb{E}_{a \sim \hat{p}_{a|q}} [\nabla_\phi r_\phi(a, q)] = \mathbb{E}_{a \sim \hat{p}_{a|q}} \left[\mathbb{E}_{\ell \sim c_\phi} [\mathbb{1}_{\ell=\text{expert}} \nabla_\phi \log c_\phi(\ell \mid a, q)] \right].$$

This corresponds to a reward signal of +1 when $\ell = \text{expert}$ (correct) and 0 when $\ell = \text{policy}$ (incorrect).

2. Policy Term ($a \sim \pi_\theta$): Note the negative sign in the original gradient formula.

$$\begin{aligned} -\mathbb{E}_{a \sim \pi_\theta} [\nabla_\phi r_\phi(a, q)] &= -\mathbb{E}_{a \sim \pi_\theta} [\nabla_\phi p_E] \\ &= \mathbb{E}_{a \sim \pi_\theta} [\nabla_\phi p_P] \quad (\text{since } \nabla_\phi p_E + \nabla_\phi p_P = 0) \\ &= \mathbb{E}_{a \sim \pi_\theta} \left[\mathbb{E}_{\ell \sim c_\phi} [\mathbb{1}_{\ell=\text{policy}} \nabla_\phi \log c_\phi(\ell \mid a, q)] \right]. \end{aligned}$$

Here, the answers come from the policy, so the correct label is policy. This corresponds to a reward signal of +1 when $\ell = \text{policy}$ (correct) and 0 when $\ell = \text{expert}$ (incorrect).

Combining both terms and grouping the expectations results in the final expression:

$$\nabla_\phi L = \frac{1}{\beta} \mathbb{E}_{q \sim \hat{p}_q} \left[\mathbb{E}_{a \sim \hat{p}_{a|q} \cup \pi_\theta} \left[\mathbb{E}_{\ell \sim c_\phi} \left[R(\ell, a, q) \nabla_\phi \log c_\phi(\ell \mid a, q) \right] \right] \right],$$

where the reward $R(\ell, a, q)$ aggregates the signs from both cases:

$$R(\ell, a, q) = \mathbb{1}_{\ell \text{ is correct}}$$

□

B FUTURE WORK

Stability in Long-form Generation. While RARO exhibits stable training dynamics on verifiable tasks (see Figure 7), we observed some instability in long-form creative tasks. As shown in Figure 6, during training, the policy and critic rewards could oscillate on the Poetry Writing task. Additionally, the validation reward similarly oscillates despite an overall upward trend. This is reminiscent of the instability observed in adversarial training for generative models, where powerful discriminators can overfit to transient artifacts and induce non-stationary learning dynamics for the generator (Karras et al., 2020). Future work will focus on developing techniques to stabilize this adversarial game in subjective domains. It will also be important to understand when such oscillations reflect true ambiguity in the task (e.g., multiple equally valid poetic styles) versus undesirable instability that harms downstream user experience.

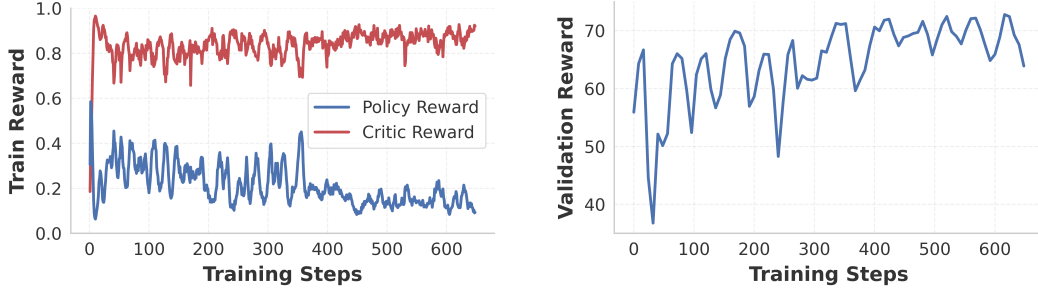


Figure 6: **Poetry Writing (7B) Training Dynamics.** During training, the policy and critic rewards oscillate on the Poetry Writing task (left). The validation reward similarly oscillates despite an overall upward trend (right).

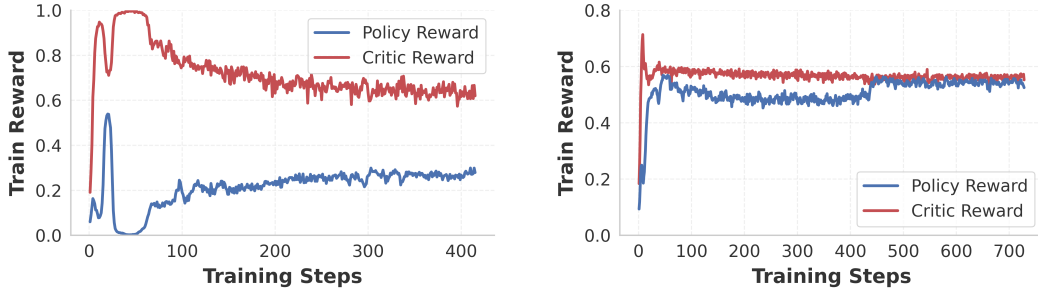


Figure 7: **Countdown and DeepMath (1.5B) Training Dynamics.** Stable policy and critic rewards during training for Countdown and DeepMath.

Sample Efficiency. While RARO achieves strong final performance, it can be less sample-efficient than RLVR when applied to verifiable tasks. As shown in Figure 8, under identical hyperparameters on the Countdown task, RARO requires more training iterations to reach performance levels comparable to RLVR. This inefficiency stems from the added complexity of jointly training a policy and critic in an adversarial game, where the critic must first learn to discriminate between policy and expert answers before providing a useful training signal. In contrast, RLVR benefits from immediate, oracle feedback. While this gap is unavoidable

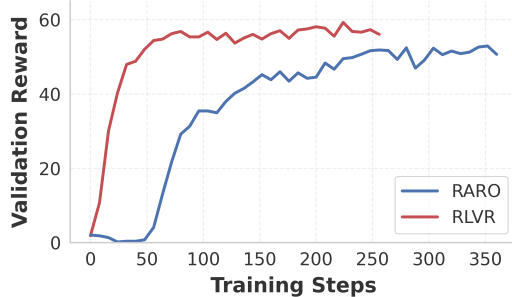


Figure 8: **Sample Efficiency Comparison.** Under the same hyperparameters, our method is less sample-efficient than RLVR on Countdown.

without access to a ground-truth verifier, future work could explore techniques to accelerate convergence, such as curriculum learning and critic pretraining. A complementary direction is to theoretically characterize the sample complexity of our relativistic adversarial objective and identify conditions under which we can provably bound the sample complexity of RARO.

Reward Interpretability. One motivation for our critic design is to produce natural-language feedback that resembles human-written explanations. However, even when the critic outputs detailed justifications, it remains challenging to extract a compact, stable, and explicitly human-interpretable rubric that governs its behavior. In practice, the critic’s preferences may be entangled across many latent factors, and at different training steps, the critic may prefer vastly different answers. Making the critic truly interpretable therefore remains an open problem at the intersection of IRL, interpretability, and value learning: promising directions include probing critic representations for concept-like features and distilling the critic into simpler rubric models.

Scaling Reasoning. We aim to scale RARO to larger base models beyond 7B parameters and beyond reasoning budget of 2048 tokens. Our results already indicate that increasing the reasoning budget—via longer chains of thought at train time and test time—can yield substantial gains. Thus, we are interested in exploring how scaling our method both in model size and reasoning budget can lead to new emerging reasoning capabilities. Another important direction is to finetune models that already exhibit strong reasoning capabilities on new tasks using RARO, so that they can rapidly adapt their reasoning strategies without requiring task-specific verifiers or human preference labels.

Broadening Non-verifiable Domains. Finally, we plan to apply our approach to a wider range of open-ended domains, such as front-end software development and long-form scientific writing, where expert demonstrations are plentiful online but reliable verifiers are absent. If successful, our approach could enable a new wave of practical LLM applications in these domains, unlocking capabilities where training signals were previously scarce or unreliable. This would allow for the deployment of robust reasoning systems in complex, real-world environments without the need for expensive or impossible-to-design verifiers.

C IMPLEMENTATION DETAILS

C.1 STABLE & EFFICIENT LEARNING

Here we describe the specific techniques that enable stable and efficient learning in RARO.

Shared LLM for Critic and Policy. While Section 3.3 provides a practical procedure for alternating updates of the policy (θ) and the critic model (ϕ), it requires training *two* reasoning LLMs and thus incurs long, token-intensive rollouts for both. To reduce memory usage and potentially promote generalization via shared representations, we ultimately use the same underlying LLM to role-play as both the critic and the policy. Our ablations (see Appendix D.2) empirically support that using a shared LLM for the critic and the policy improves performance.

Data Mixing. In addition, by sharing the same underlying LLM, we can substantially simplify the concrete algorithm by *mixing* both the critic and policy rollouts in the same batch to compute advantage and loss. This allows us to remove the need for alternating updates between the critic and the policy and instead perform all updates in a single batch. Furthermore, this setup allows us to easily control the “strength” of the policy and the critic by adjusting the weight of the critic and policy loss in the combined objective.

Catastrophic Forgetting & Replay Buffer. In GAN training (Goodfellow et al., 2014), the discriminator often suffers from catastrophic forgetting as the generator “cycles” among modes to fool it (Thanh-Tung & Tran, 2020; Liang & Carin, 2018). We observe a similar problem in our setting, where policy learns to cycle through a fixed set of strategies to “hack” the critic reward (see Appendix D.2). To mitigate this, we construct half of the critic prompts from a replay buffer of all past policy rollouts, while the other half are sampled from the current batch of policy rollouts, ensuring the critic is continually trained on every mode of “attack” discovered by the policy.

GRPO & Optimizations. Finally, we address several practical issues when implementing the concrete algorithm. When querying the critic to reward policy rollouts, occasional formatting or networking failures produce invalid rewards; we exclude the affected rollouts from the loss by masking them during backpropagation. Following DAPO (Yu et al., 2025), we also apply over-length filtering: any policy or critic rollout that exceeds a specified token-length threshold is excluded from the objective computation. Finally, inspired by Dr. GRPO (Liu et al., 2025), we remove advantage normalization and response-length normalization, which we found to introduce bias in our setting.

C.2 DATASETS

Countdown. We use a 24-style variant of the Countdown arithmetic puzzle, where the goal is to combine four integers using basic arithmetic operations to obtain the target value 24. Instances are synthetically generated via an exhaustive search over all possible combination of operands from $[1, 50]$ and operations from $\{+, -, \times, \div\}$. The instances are then annotated with expert demonstrations by GPT-5 (OpenAI, 2025), discarding instances that GPT-5 cannot solve. The resulting dataset contains 131k total problems, from which we reserve 1024 tasks as a held-out test set. For this task, the final answer is exactly verifiable via a straightforward expression computation, while the underlying search over expressions is substantially more complex.

DeepMath. To evaluate our method on general math reasoning domain, we use the DeepMath dataset (He et al., 2025), which consists of approximately 103k diverse and high-quality math problems with well-defined ground-truth answers. We utilize the full DeepMath-103K dataset for training and hold out 635 decontaminated problems as a test set. While the dataset provides example reasoning traces beyond ground-truth answers, we discard them in all of our baselines for fairness as our method is not designed to leverage them.

Poetry Writing. We construct our poetry writing task from a pre-collected corpus¹ of roughly 40k English-language poems sourced from Poetry Foundation². For each poem, we automatically

¹ jnb666/poems ² Poetry Foundation

generate a short human-style prompt using GPT-5 and treat the original poem as the expert demonstration. Out of the 40k poems, we reserve 256 poems at random as our test set. Since poetry writing does not admit an objective verifier, we evaluate RARO and baselines using GPT-5. Specifically, we set up two evaluation metrics: *scalar score* and *win-rate*. The scalar score is measured by prompting GPT-5 to score the poem on a scale of 1-7 then normalized to 0-100, considering both prompt adherence and literary quality. The win-rate is measured by supplying GPT-5 with both the policy and expert poems and prompting it to determine which poem has higher overall quality.

C.3 IMPLEMENTATION STACK

Supervised methods (SFT and Rationalization). We train the SFT and Rationalization baselines using Together AI’s managed fine-tuning service. While we monitor the validation loss during training, we ultimately select the checkpoint for evaluation based on the best validation reward.

Iterative Direct Preference Optimization (DPO). Our iterative DPO baselines are implemented using the `trl` library with PyTorch FSDP2 enabled to support efficient distributed training at all model scales. For evaluation, we similarly select the checkpoint that maximizes the validation reward. We repeat this process for 3 rounds.

RL-based methods (RL-Logit, RLVR, and RARO). All RL-based methods—RL-Logit, RLVR, and RARO—are implemented on top of the `verl` framework (Sheng et al., 2024), a flexible and efficient RL framework for LLM post-training. For RLVR, we use the default GRPO implementation in `verl` without modification, with the reward given by binary ground-truth verifier. For RL-Logit, we extend `verl` with a custom reward function that computes the scalar reward from the policy logits on expert answers conditioned on the question and generated CoT tokens. To stabilize training and avoid vanishing or exploding rewards, we use two reward variants:

- Log-probability variant: $\max(0.1 \times \log \pi_{\theta}(a^* \mid q, z), -1.0)$
- Perplexity variant: $10.0 \times \exp(\text{mean}(\log \pi_{\theta}(a^* \mid q, z)))$

For RARO, we further modify the framework to (i) support rewards derived from critic rollouts instead of direct verifiers, and (ii) implement a replay buffer and mixed data pipeline that interleaves policy and critic rollouts for stable joint training of the policy and critic.

Compute setup. Unless otherwise specified, all non-RL methods (SFT, Rationalization, and DPO) are trained on a single node with $8 \times \text{H100}$ GPUs, regardless of model size or reasoning token budget. RL-style methods are more compute intensive: we train RLVR, RL-Logit, and our method on 2 nodes with $8 \times \text{H100}$ GPUs each for the 1.5B and 3B models, and on 4 such nodes (32 H100 GPUs in total) for the 7B model.

C.4 HYPERPARAMETERS

We summarize the core optimization hyperparameters used for all methods in Tables 4 and 5. Unless otherwise specified, these settings are shared across all tasks (Countdown, DeepMath, and Poetry Writing) and model sizes described in Section 4.

SFT & Rationalization		Iterative DPO		RLVR & RL-Logit & RARO	
Hparam	Value	Hparam	Value	Hparam	Value
Epochs	4	Epochs	1	Rollout batch	1024
Batch size	8	Batch size	128	Rollout temp.	1.0
Optim	AdamW	Optim	AdamW	Group size	16
LR	1×10^{-5}	LR	1×10^{-6}	Optim	AdamW
Weight decay	0.02	Weight decay	0.01	LR	1×10^{-6}
Max grad. norm	1.0	Max grad. norm	1.0	Weight decay	0.01
LR Sched	Cosine	LR Sched	Cosine	Max grad. norm	1.0
Warmup ratio	0.05	Warmup ratio	0.05	Train batch	256
Min LR ratio	0.03	Min LR ratio	0.03	Clip ratio	[0.2, 0.28]
Num cycles	0.5	Num cycles	0.5	KL coeff.	10^{-3}
		β_{DPO}	0.1		

Table 4: **Shared hyperparameters across ours and baselines.** SFT and Rationalization share the same AdamW optimizer setup, while DPO uses a different configuration. All three share the same cosine learning-rate schedule. RLVR, RL-Logit, and RARO share the same underlying GRPO setup as described in Section 3.

RARO (Countdown)

Hparam	Value
τ_{pol}	0.6
τ_{crit}	0.55
λ_{pol}	1/2
λ_{crit}	1/2

RARO (DeepMath)

Hparam	Value
τ_{pol}	0.6
τ_{crit}	0.55
λ_{pol}	1/9
λ_{crit}	8/9

RARO (Poetry Writing)

Hparam	Value
τ_{pol}	0.6
τ_{crit}	0.5
λ_{pol}	1/3
λ_{crit}	2/3

Table 5: **Hyperparameters for our method.** We use the relativistic critic and shared-LLM training setup described in Section 3, with tie rewards ($\tau_{\text{pol}}, \tau_{\text{crit}}$) and loss weights ($\lambda_{\text{pol}}, \lambda_{\text{crit}}$) chosen to balance exploration and critic supervision for each task.

C.5 TEST-TIME SCALING ALGORITHM

Here, we provide additional details for our Test-Time Scaling (TTS) algorithm. As described in Algorithm 3, we implement TTS via a single-elimination tournament. Given a pool of candidate responses \mathcal{Y} generated by the policy, we iteratively pair them and use the learned critic C_ϕ to select the better response. To mitigate the variance in the critic’s generated reasoning, for each pair of responses (y_A, y_B) , we sample the critic K times and use a majority vote to determine the winner. We use $K = 4$ for all our TTS experiments. Tables 12 and 14 present the full results of RARO with TTS compared to baselines with identical TTS settings.

Algorithm 3 Single-Elimination Tournament for Test-Time Scaling

Require: Prompt x , Candidates \mathcal{Y} , Critic C_ϕ , Votes K

Ensure: Best response y^*

```

1: while  $|\mathcal{Y}| > 1$  do
2:    $\mathcal{Y}_{\text{next}} \leftarrow \emptyset$ 
3:   for  $i = 1$  to  $|\mathcal{Y}|$  step 2 do
4:     if  $i == |\mathcal{Y}|$  then  $\mathcal{Y}_{\text{next}}.\text{append}(\mathcal{Y}[i]);$  continue
5:   end if
6:    $y_A, y_B \leftarrow \mathcal{Y}[i], \mathcal{Y}[i + 1]$ 
7:    $v_A \leftarrow \sum_{k=1}^K \mathbb{I}(C_\phi(\cdot | x, y_A, y_B) \text{ favors } A)$ 
8:    $\mathcal{Y}_{\text{next}}.\text{append}(v_A > K/2 ? y_A : y_B)$ 
9: end for
10:  $\mathcal{Y} \leftarrow \mathcal{Y}_{\text{next}}$ 
11: end while
12: return  $\mathcal{Y}[1]$ 

```

D ADDITIONAL RESULTS

D.1 MODEL SIZE SCALING ON COUNTDOWN

We systematically study the effect of scaling model size on the performance on Countdown. In addition to the main results at 1.5B reported in Section 5, we conducted additional experiments at 3B. The verifiable baseline, RLVR, exhibits a performance regression, dropping from 57.7% at 1.5B to 53.5% at 3B (Figure 9). Similarly, we observe that the performance of RARO also degrades from 54.4% to 49.7% at 3B. Furthermore, as illustrated in Figure 10, after initial improvements, both RLVR and RARO performance actively decreases as training progresses. While we do not have a definitive explanation, we hypothesize that larger models may be more prone to the training-inference log-probability mismatch problem (Yao et al., 2025), leading to degradation when scaling model capacity. These results indicate that RARO does not inherently contribute to the performance plateau; rather, it is a systematic problem that we observe with RLVR as well.

Method	1.5B accuracy (%) \uparrow	3B accuracy (%) \uparrow
RLVR	57.7 ± 1.6	53.5 ± 1.6
RARO	54.4 ± 1.5	49.7 ± 1.6

Table 6: Model Size Scaling on Countdown.

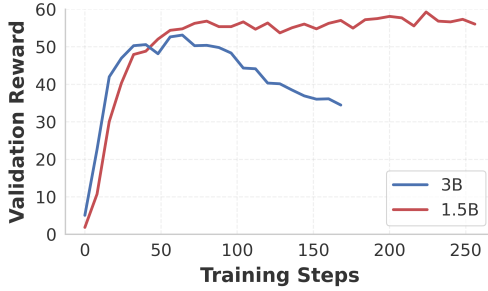


Figure 9: RLVR with a 3B model achieves lower performance than with a 1.5B model.

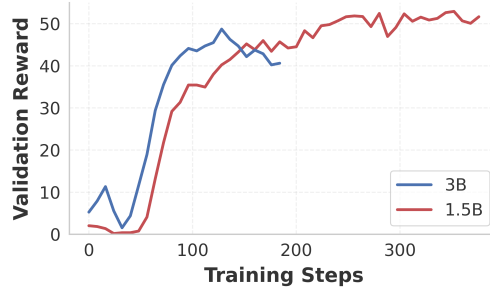


Figure 10: RARO similarly degrades from 1.5B to 3B.

D.2 ABLATION STUDIES

We conduct Leave-One-Out (LOO) ablations on the DeepMath dataset at 1.5B to isolate the contribution of each component in our framework. As summarized in Table 7, removing any single component—the shared LLM, relativistic critic, critic reasoning, tie option, or replay buffer—results in a significant performance degradation compared to our full method (41.3%). This uniform drop confirms that all designed mechanisms are essential for the method’s overall effectiveness.

Beyond aggregate metrics, we observe distinct failure modes associated with particular missing components, illustrated by the training dynamics.

Method	DeepMath 1.5B accuracy (%) \uparrow
w/o critic reasoning	35.9 ± 1.9
w/o relativistic critic	36.9 ± 1.9
w/o tie option	38.6 ± 1.9
w/o replay buffer	35.4 ± 1.8
w/o shared LLM	39.4 ± 1.9
RARO	41.3 ± 1.9

Table 7: **Ablation results on DeepMath 1.5B.** Removing any component leads to performance degradation.

Necessity of Critic Reasoning. RARO relies on the critic performing explicit CoT reasoning before providing a final judgment. When this reasoning step is removed, the critic loses its capacity to make meaningful distinctions between responses. As shown in Figure 11, instead of providing consistent signals, it collapses into a degenerate state, consistently outputting a `tie` response regardless of the quality of the policy or expert answer. This failure prevents the policy from receiving useful reward signals, stalling learning.



Figure 11: **No Critic Reasoning.** Without critic reasoning, the critic always outputs `tie`, preventing the policy from learning.

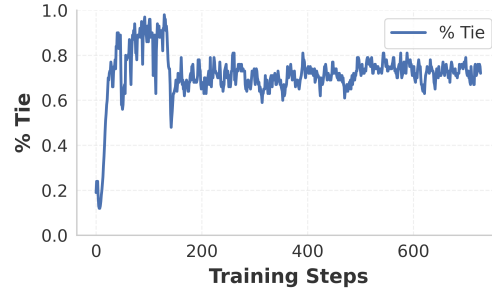


Figure 12: **Tie Distribution.** The critic learns to output `tie` stably for around 70% of the outputs after around 150 training steps.

Importance of Relativistic Setup. The relativistic critic evaluates the policy’s answer and the expert’s answer in a pairwise fashion rather than in isolation. Without this relativistic setup, the reward signal perceived by the policy exhibits significantly higher variance during training, as illustrated in Figure 13. This instability suggests that the reference answer serves as a crucial anchor enabling stable optimization. We further demonstrate that the critic successfully learns to utilize the `tie` option defined in our relativistic setup. As shown in Figure 12, the critic learns to output `tie` stably for around 70% of the outputs after around 150 training steps. In addition, as shown in Table 7, without the `tie` option, the final policy’s performance drops from 41.3% to 38.6%, indicating that the addition of the `tie` option contributes to the final policy performance.

Role of the Replay Buffer. Finally, the replay buffer is critical for preventing cycling dynamics. As shown in Figure 14, removing the replay buffer causes the critic’s training reward to oscillate severely after around 300 training steps. This suggests that the policy learns to exploit the critic’s forgetfulness by cycling through adversarial patterns that temporarily fool the critic. This interaction eventually destabilizes the critic completely, leading it to default to a `tie` output, effectively halting progress.

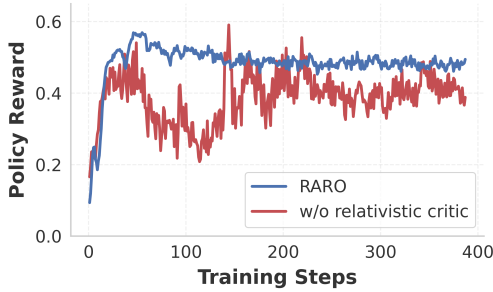


Figure 13: **No Relativistic Setup.** Without the relativistic setup, the policy reward during training exhibits high variance.

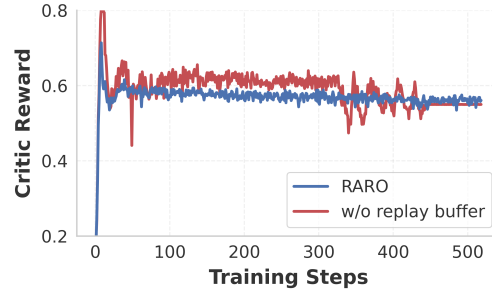


Figure 14: **No Replay Buffer.** Without a replay buffer, the training suffers from severe oscillations and eventual collapse.

E ADDITIONAL TABLES & FIGURES

Budget	256	512	1024	2048	4096
SFT	40.7 ± 1.6	40.7 ± 1.6	40.7 ± 1.6	40.7 ± 1.6	40.7 ± 1.6
RARO	33.1 ± 1.5	40.9 ± 1.5	51.2 ± 1.6	54.4 ± 1.5	61.3 ± 1.5

Table 8: Tabular data for Countdown reasoning budget scaling results. Notably, result reported at a budget of 4096 tokens is derived from extrapolating test-time reasoning budget of the model trained at 2048 tokens.

N	1.5B	3B	7B
1	41.6 ± 1.9	47.5 ± 2.0	57.8 ± 1.9
2	45.0 ± 2.0	51.7 ± 2.0	61.2 ± 1.9
4	45.1 ± 2.0	54.2 ± 2.0	63.4 ± 2.0
8	46.2 ± 2.0	54.8 ± 2.0	65.3 ± 1.9
16	53.6 ± 2.3	57.9 ± 2.0	68.4 ± 2.0

Table 9: Tabular data for RARO’s TTS scaling results on DeepMath.

Method	Countdown accuracy (%) \uparrow
RLVR (<i>with verifier</i>)	57.7 ± 1.6
Base	2.0 ± 0.4
SFT	40.7 ± 1.6
Rationalization	12.5 ± 1.0
DPO	
Round 1	40.4 ± 1.5
Round 2	32.5 ± 1.4
Round 3	32.2 ± 1.4
RL-Logits	2.2 ± 0.4
RARO	54.4 ± 1.5

Table 11: Complete results for Countdown at 1.5B.

N	1.5B	3B	7B
1	50.9 ± 1.9	55.8 ± 2.0	66.2 ± 2.0
2	55.5 ± 1.9	63.4 ± 1.9	68.9 ± 1.9
4	59.6 ± 1.9	68.6 ± 1.8	69.8 ± 1.9
8	64.4 ± 1.9	72.5 ± 1.7	71.5 ± 1.9
16	66.1 ± 1.8	75.8 ± 1.7	76.9 ± 1.9

Table 10: Tabular data for the RLVR’s TTS scaling results on DeepMath.

Method	Countdown accuracy (%) \uparrow
RLVR (<i>with verifier</i>)	71.0 ± 1.5
Base	4.2 ± 0.6
SFT	42.4 ± 1.6
Rationalization	11.2 ± 1.0
DPO	
Round 1	43.1 ± 1.6
Round 2	34.8 ± 1.5
Round 3	31.6 ± 1.4
RL-Logits	3.1 ± 0.5
RARO	75.0 ± 1.4

Table 12: Complete results for Countdown at 1.5B with TTS.

Method	DeepMath accuracy (%) \uparrow	Poetry score (0-100) \uparrow	Poetry win-rate (%) \uparrow (vs. expert)
1.5B			
RLVR (<i>with verifier</i>)	50.9 \pm 1.9	N/A	N/A
Base	29.6 \pm 1.9	35.0 \pm 0.9	0.0 \pm 0.0
SFT	35.7 \pm 1.8	53.7 \pm 1.0	2.3 \pm 1.0
Rationalization	34.5 \pm 2.0	35.6 \pm 1.6	0.8 \pm 0.5
DPO			
Round 1	29.9 \pm 1.8	48.6 \pm 0.9	0.0 \pm 0.0
Round 2	33.0 \pm 1.9	10.3 \pm 0.5	0.0 \pm 0.0
Round 3	29.6 \pm 1.8	29.3 \pm 1.0	0.0 \pm 0.0
RL-Logits	37.7 \pm 1.9	36.4 \pm 0.7	0.0 \pm 0.0
RARO	41.3 \pm 1.9	67.8 \pm 0.8	7.8 \pm 1.7
3B			
RLVR (<i>with verifier</i>)	55.8 \pm 2.0	N/A	N/A
Base	39.4 \pm 1.9	46.5 \pm 0.9	0.0 \pm 0.0
SFT	39.0 \pm 1.9	57.4 \pm 1.0	2.3 \pm 1.0
Rationalization	32.3 \pm 1.9	30.8 \pm 1.9	0.4 \pm 0.4
DPO			
Round 1	33.2 \pm 1.8	58.7 \pm 0.9	1.2 \pm 0.7
Round 2	34.2 \pm 1.9	57.1 \pm 1.0	0.0 \pm 0.0
Round 3	31.9 \pm 1.8	69.8 \pm 0.8	6.6 \pm 1.5
RL-Logits	43.1 \pm 2.0	46.9 \pm 0.8	0.4 \pm 0.4
RARO	49.1 \pm 1.9	71.9 \pm 0.8	17.2 \pm 2.4
7B			
RLVR (<i>with verifier</i>)	66.2 \pm 1.9	N/A	N/A
Base	44.2 \pm 2.1	54.0 \pm 0.9	1.2 \pm 0.7
SFT	42.3 \pm 1.9	65.4 \pm 1.0	5.9 \pm 1.4
Rationalization	48.6 \pm 1.9	57.7 \pm 1.2	5.1 \pm 1.3
DPO			
Round 1	36.9 \pm 2.0	61.6 \pm 0.9	3.5 \pm 1.1
Round 2	36.5 \pm 1.9	66.5 \pm 0.9	5.1 \pm 1.4
Round 3	32.8 \pm 1.9	54.1 \pm 1.6	3.9 \pm 1.2
RL-Logits	49.3 \pm 2.0	55.4 \pm 0.8	3.9 \pm 1.2
RARO	57.5 \pm 2.0	77.3 \pm 0.8	25.0 \pm 2.6

Table 13: **Main results for DeepMath and Poetry.** We report the average and standard deviation of evaluation metrics for DeepMath and Poetry Writing across model scales with an reasoning token budget of 2048.

Method	DeepMath accuracy (%) \uparrow	Poetry score (0-100) \uparrow	Poetry win-rate (%) \uparrow (<i>vs. expert</i>)
1.5B			
RLVR (<i>with verifier</i>)	59.7 ± 2.3	N/A	N/A
Base	26.9 ± 6.2	36.4 ± 0.7	0.0 ± 0.0
SFT	37.3 ± 1.9	55.1 ± 1.1	1.6 ± 0.8
Rationalization	42.6 ± 2.8	41.2 ± 1.5	0.0 ± 0.0
DPO			
Round 1	31.7 ± 1.9	49.9 ± 0.9	0.0 ± 0.0
Round 2	34.0 ± 1.9	9.5 ± 0.4	0.0 ± 0.0
Round 3	30.4 ± 1.9	30.1 ± 1.1	0.0 ± 0.0
RL-Logits	41.3 ± 2.0	38.0 ± 0.7	0.0 ± 0.0
RARO	53.6 ± 2.3	67.7 ± 0.8	8.2 ± 1.8
3B			
RLVR (<i>with verifier</i>)	67.5 ± 2.1	N/A	N/A
Base	49.7 ± 2.9	50.8 ± 0.7	0.4 ± 0.4
SFT	39.0 ± 2.0	57.2 ± 1.0	1.3 ± 0.7
Rationalization	42.7 ± 2.6	50.2 ± 1.4	2.0 ± 0.8
DPO			
Round 1	34.6 ± 2.0	57.5 ± 0.9	2.1 ± 0.9
Round 2	35.7 ± 1.9	55.8 ± 0.9	1.6 ± 0.7
Round 3	34.2 ± 1.9	70.3 ± 0.8	9.0 ± 1.8
RL-Logits	44.0 ± 2.1	51.1 ± 0.7	0.4 ± 0.4
RARO	57.9 ± 2.0	74.1 ± 0.8	21.9 ± 2.6
7B			
RLVR (<i>with verifier</i>)	76.9 ± 1.9	N/A	N/A
Base	50.8 ± 2.6	58.8 ± 0.6	2.3 ± 0.9
SFT	42.1 ± 2.0	63.9 ± 0.9	4.7 ± 1.4
Rationalization	58.4 ± 2.3	55.1 ± 1.2	2.0 ± 0.9
DPO			
Round 1	42.9 ± 2.3	60.8 ± 0.9	3.5 ± 1.1
Round 2	36.8 ± 1.9	67.2 ± 0.9	4.3 ± 1.3
Round 3	42.9 ± 2.3	53.7 ± 1.6	2.7 ± 1.0
RL-Logits	51.0 ± 2.1	60.9 ± 0.6	1.6 ± 0.8
RARO	68.4 ± 2.0	79.2 ± 0.8	25.0 ± 2.7

Table 14: **Main results for DeepMath and Poetry with TTS.** Comparison of RARO against baselines with identical Test-Time Scaling settings.

Countdown

Use the four numbers 19, 11, 48, and 6 to create an expression that equals 24.

Remember:

- Use each number exactly once
- You can only use +, -, *, / and parentheses
- The expression must be valid Python code that evaluates to 24

Think through different combinations and show your reasoning. Once you find a valid solution, put your final answer inside `\boxed{}` tags.

For example, if the solution is $(8 - 2) * 4 + 0$, you would write: `\boxed{(8 - 2) * 4 + 0}`

The expression inside `\boxed{}` must be directly evaluable in Python and should equal 24.

RARO Policy

<think>

To find an expression using the four numbers 19, 11, 48, and 6 that equals 24, let's try different combinations.

1. $(48 - 11) * (19 - 6) = 37 * 13 = 481$ (too high)
2. $(48 - 19) * (11 - 6) = 29 * 5 = 145$ (too high)
3. $(48 * 11) / (19 - 6) = 528 / 13 = 40.615$ (too high)
4. $48 / (19 - 11) + 6 = 48 / 8 + 6 = 6 + 6 = 12$ (too low)
5. $(48 - 11) * (19 / 6) = 37 * 3.167 = 115.167$ (too high)
6. $(48 / (19 - 11)) * 6 = (48 / 8) * 6 = 6 * 6 = 36$ (too low)
7. $(48 - 11) + (19 - 6) = 37 + 13 = 50$ (too low)
8. $48 / (19 - 6) + 11 = 48 / 13 + 11 = 3.769 + 11 = 14.769$ (too low)
9. $11 * (48 / (19 - 6)) = 11 * (48 / 13) = 11 * 3.769 = 41.459$ (too low)
10. $(48 / 6) + (19 - 11) = 8 + 8 = 16$ (too low)
11. $19 - (48 / (11 - 6)) = 19 - (48 / 5) = 19 - 9.6 = 9.4$ (too low)
12. $(48 / (19 - 6)) + 11 = (48 / 13) + 11 = 3.769 + 11 = 14.769$ (too low)
13. $(48 - 11) + (19 - 6) = 37 + 13 = 50$ (too low)
14. $19 - (48 / (11 + 6)) = 19 - (48 / 17) = 19 - 2.764 = 16.236$ (too low)
15. $(19 - 11) * (48 / 6) = 8 * 8 = 64$ (too high)
16. $(19 + 11) - (48 / 6) = 30 - 8 = 22$ (too low)
17. $48 / (11 - (19 - 6)) = 48 / (11 - 13) = 48 / -2 = -24$ (too low)
18. $(48 / 6) + (19 - 11) = 8 + 8 = 16$ (too low)
19. $(48 / (19 - 6)) + 11 = (48 / 13) + 11 = 3.769 + 11 = 14.769$ (too low)
20. $48 / (19 - (11 + 6)) = 48 / (19 - 17) = 48 / 2 = 24$ (correct)

The final answer is: `\boxed{48 / (19 - (11 + 6))}`

</think>

`48/(19 - (11 + 6))`

Figure 15: Full qualitative example for the RARO policy for Countdown at 1.5B.

DeepMath

Find the equation of the normal line to the curve $(x^2 + y^2)^{3/2} = 2xy$ at the point $\left(\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}\right)$.

RARO Policy

<think>

To find the equation of the normal line to the curve $(x^2 + y^2)^{3/2} = 2xy$ at the point $\left(\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}\right)$, we need to follow these steps:

1. Differentiate the curve implicitly to find the slope of the tangent line at the given point.
2. Use the slope of the tangent line to find the slope of the normal line.
3. Write the equation of the normal line using the point-slope form.

Let's start with implicit differentiation. Given the equation:

$$(x^2 + y^2)^{3/2} = 2xy$$

Differentiate both sides with respect to x :

$$\frac{d}{dx} \left((x^2 + y^2)^{3/2} \right) = \frac{d}{dx} (2xy)$$

Using the chain rule on the left side:

$$\frac{3}{2}(x^2 + y^2)^{1/2} \cdot \frac{d}{dx}(x^2 + y^2) = 2y + 2x \frac{dy}{dx}$$

Now, differentiate $x^2 + y^2$ with respect to x :

$$\frac{3}{2}(x^2 + y^2)^{1/2} (2x + 2y \frac{dy}{dx}) = 2y + 2x \frac{dy}{dx}$$

Simplify the left side:

$$3(x^2 + y^2)^{1/2} (x + y \frac{dy}{dx}) = 2y + 2x \frac{dy}{dx}$$

Distribute and collect terms involving $\frac{dy}{dx}$ on one side:

$$3(x^2 + y^2)^{1/2} x + 3(x^2 + y^2)^{1/2} y \frac{dy}{dx} = 2y + 2x \frac{dy}{dx}$$

$$3(x^2 + y^2)^{1/2} y \frac{dy}{dx} - 2x \frac{dy}{dx} = 2y - 3(x^2 + y^2)^{1/2} x$$

Factor out $\frac{dy}{dx}$ on the left side:

$$\frac{dy}{dx} \left(3(x^2 + y^2)^{1/2} y - 2x \right) = 2y - 3(x^2 + y^2)^{1/2} x$$

Solve for $\frac{dy}{dx}$:

$$\frac{dy}{dx} = \frac{2y - 3(x^2 + y^2)^{1/2} x}{3(x^2 + y^2)^{1/2} y - 2x}$$

Next, we need to find the slope of the tangent line at the point $\left(\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}\right)$: Substitute $x = \frac{1}{\sqrt{2}}$ and $y = \frac{1}{\sqrt{2}}$ into the derivative:

$$\frac{dy}{dx} = \frac{2\left(\frac{1}{\sqrt{2}}\right) - 3\left(\left(\left(\frac{1}{\sqrt{2}}\right)^2 + \left(\frac{1}{\sqrt{2}}\right)^2\right)\right)^{1/2} \left(\frac{1}{\sqrt{2}}\right)}{3\left(\left(\left(\frac{1}{\sqrt{2}}\right)^2 + \left(\frac{1}{\sqrt{2}}\right)^2\right)\right)^{1/2} \left(\frac{1}{\sqrt{2}}\right) - 2\left(\frac{1}{\sqrt{2}}\right)}$$

Simplify the terms inside:

$$x^2 + y^2 = \left(\frac{1}{\sqrt{2}}\right)^2 + \left(\frac{1}{\sqrt{2}}\right)^2 = \frac{1}{2} + \frac{1}{2} = 1$$

So:

$$\frac{dy}{dx} = \frac{2\left(\frac{1}{\sqrt{2}}\right) - 3(1)^{1/2}\left(\frac{1}{\sqrt{2}}\right)}{3(1)^{1/2}\left(\frac{1}{\sqrt{2}}\right) - 2\left(\frac{1}{\sqrt{2}}\right)} = \frac{\frac{2}{\sqrt{2}} - \frac{3}{\sqrt{2}}}{\frac{3}{\sqrt{2}} - \frac{2}{\sqrt{2}}} = \frac{\frac{2-3}{\sqrt{2}}}{\frac{3-2}{\sqrt{2}}} = \frac{-1}{1} = -1$$

The slope of the tangent line at $\left(\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}\right)$ is -1 . The slope of the normal line is the negative reciprocal of -1 , which is 1 .

Now, use the point-slope form of the equation of a line $y - y_1 = m(x - x_1)$, where m is the slope and (x_1, y_1) is the point:

$$y - \frac{1}{\sqrt{2}} = 1\left(x - \frac{1}{\sqrt{2}}\right)$$

Simplify:

$$\begin{aligned} y - \frac{1}{\sqrt{2}} &= x - \frac{1}{\sqrt{2}} \\ y &= x \end{aligned}$$

Thus, the equation of the normal line is:

$$\boxed{y = x}$$

</think>

$$\boxed{y = x}$$

Figure 16: Full qualitative example for the RARO policy for DeepMath at 7B.

Poetry Writing

a poem about a child's fragmented memory of a father leaving, told in intimate, sensory free verse

Please carefully think about how to create an artistic poem while adhering to the prompt, and please enclose the final version of your poem (along with the title) in `<poem></poem>` tags

RARO Policy

`<think>`

To create such a poem, I'd:

1. Focus on sensory details that might linger in a child's memory.
2. Use free verse, with unrhymed, natural cadences to convey the fragmented and stream-of-consciousness nature of recollections.
3. Include elements that represent the end of a relationship, like a suitcase, luggage, or a car, without explicitly stating the scenario.
4. Incorporate physical and emotional sensations that capture the essence of the scene.

`</think>`

`<poem>`

One Memory of My Father Leaving

There was the sound
of a suitcase rolling
on the hallway carpet;

the thud of it
being set down in the sunroom
and a shadow of it carried away

by someone going somewhere.

It smelled of leather, or brown soap,
or something carried in it
-like salt air, or bare shoulders,

or a man thinking
and trying not to cry.

`</poem>`

Figure 17: Full qualitative example for the RARO policy for Poetry Writing at 7B.

Countdown

You are an expert mathematics critic whose goal is to compare two answers to a math problem and determine which one is correct.

...

Question:

<question>

Use the four numbers 20, 45, 10, and 23 to create an expression that equals 24.

...

</question>

Answer 1:

<answer_1>

(45 - 23) + (20/10)

</answer_1>

Answer 2:

<answer_2>

(20 + 45 * 2) - 23

</answer_2>

RARO Critic

<think>

To determine which answer is correct, let's carefully analyze both solutions.

For Answer 1: (45 - 23) + (20/10)

Let's follow these steps:

1. Perform the subtraction inside the first set of parentheses: $45 - 23 = 22$
2. Perform the division inside the second set of parentheses: $20/10 = 2$
3. Add the results: $22 + 2 = 24$

Answer 1 is correct.

For Answer 2: (20 + 45 * 2) - 23

Let's follow these steps:

1. Perform the multiplication inside the parentheses: $45 \times 2 = 90$
2. Add the numbers inside the parentheses: $20 + 90 = 110$
3. Subtract 23: $110 - 23 = 87$

Answer 2 is incorrect.

</think>

Answer 1

Figure 18: Qualitative example of the RARO critic for Countdown at 1.5B.

DeepMath

You are an expert mathematics critic whose goal is to compare two answers to a math problem and determine which one is correct.

...

Question:

<question>

Evaluate the double integral $\int \int_R x^2 + y^2 dx dy$ where R is the region bounded by the circle $x^2 + y^2 = 4$ and the lines $y = 0$ and $y = x$.

</question>

Answer 1:

<answer.1>

$$-\frac{8\pi}{5}$$

</answer.1>

Answer 2:

<answer.2>

$$\pi$$

</answer.2>

RARO Critic

<think>

Let's evaluate the double integral $\int \int_R x^2 + y^2 dx dy$ where R is the region bounded by the circle $x^2 + y^2 = 4$ and the lines $y = 0$ and $y = x$.

To solve the integral, we can convert to polar coordinates. The circle $x^2 + y^2 = 4$ has a radius of 2, so in polar coordinates, the region R is described by $0 \leq r \leq 2$ and $0 \leq \theta \leq \frac{\pi}{4}$ (considering the quadrant where the region is). The integrand in polar coordinates is $x^2 + y^2 = r^2$.

The Jacobian of the transformation from Cartesian to polar coordinates is r , so the integral becomes:

$$\iint_R x^2 + y^2 dx dy = \int_0^{\frac{\pi}{4}} \int_0^2 r^2 \cdot r dr d\theta = \int_0^{\frac{\pi}{4}} \int_0^2 r^3 dr d\theta.$$

First, we integrate with respect to r :

$$\int_0^2 r^3 dr = \left[\frac{r^4}{4} \right]_0^2 = \frac{2^4}{4} - \frac{0^4}{4} = \frac{16}{4} = 4.$$

Next, we integrate with respect to θ :

$$\int_0^{\frac{\pi}{4}} 4 d\theta = 4 [\theta]_0^{\frac{\pi}{4}} = 4 \left(\frac{\pi}{4} - 0 \right) = \pi.$$

Therefore, the value of the double integral is π .

So, the answer is π .

</think>

Answer 2

Figure 19: Qualitative example of the RARO critic for DeepMath at 7B.

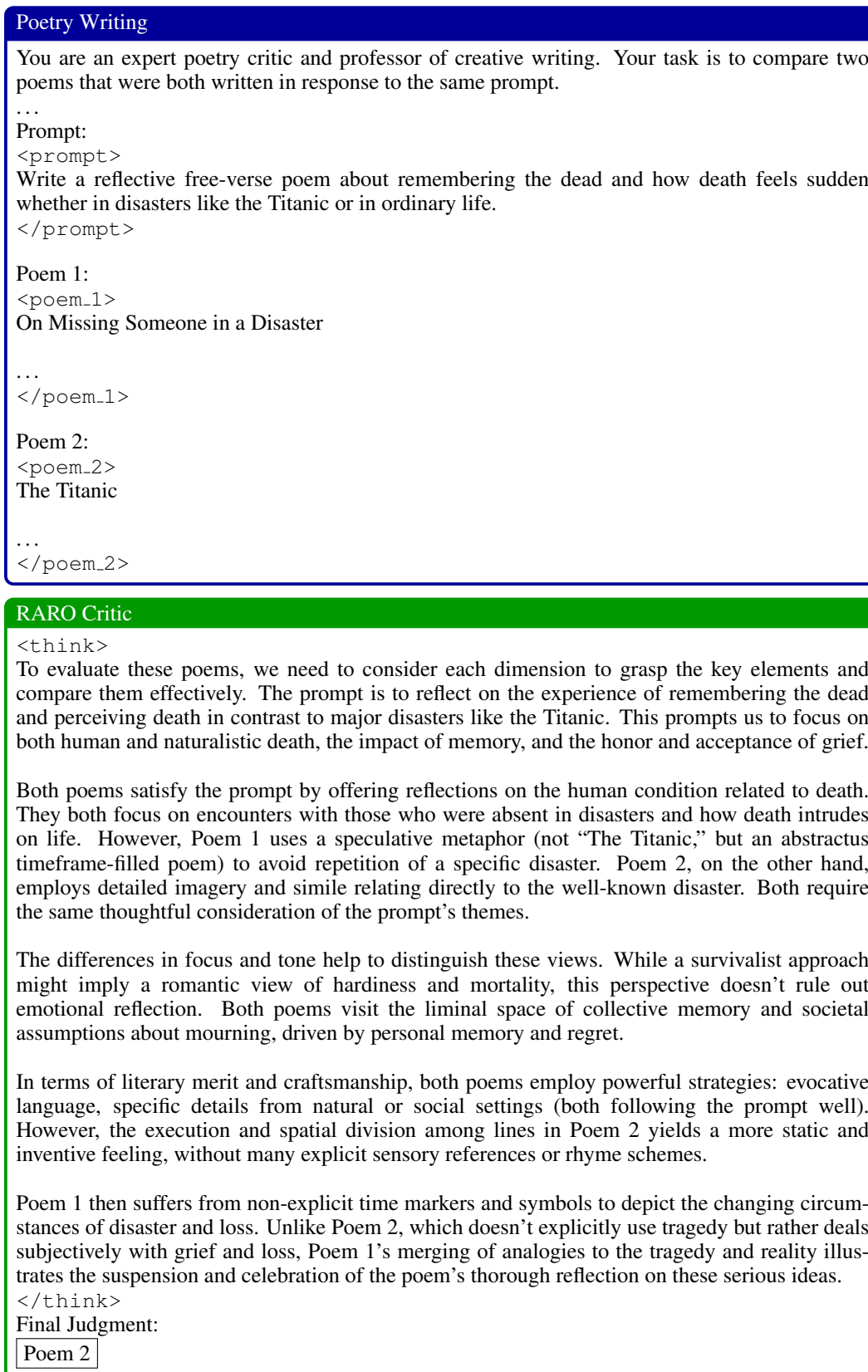


Figure 20: Qualitative example of the RARO critic for Poetry Writing at 7B.